Cover letter

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Title of the paper: Uncertain estimation-based Motion planning algorithms for mobile robots

List of modifications:

* The title was changed.
* The abstract was rewritten.
* The number of the reference list has been enlarged by presenting online motion planning methods in Previous work (Section 2.).
* The Artificial Potential field method was expressed (at the end of Section 2.).
* Another motion planning algorithm (based on the Artificial potential field method), using the uncertainties, was introduced (Section 4.3.).
* The introduced cost function based motion planning algorithm was compared with the extended APF method in different cases (Section 5.).
* The CopeliaSim simulation environment was also used and presented (Section 6.)
* The Conclusion part was rewritten (Section 7.).